Spatial-frequency cutoff requirements for pattern recognition in central and peripheral vision

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Abstract

It is well known that object recognition requires spatial frequencies exceeding some critical cutoff value. People with central scotomas who rely on peripheral vision have substantial difficulty with reading and face recognition. Deficiencies of pattern recognition in peripheral vision might result in higher cutoff requirements, and may contribute to the functional problems of people with central-field loss. Here we asked about differences in spatial-cutoff requirements in central and peripheral vision for letter and face recognition.

The stimuli were the 26 letters of the English alphabet and 26 celebrity faces. Each image was blurred using a low-pass filter in the spatial frequency domain. Critical cutoffs (defined as the minimum low-pass filter cutoff yielding 80% accuracy) were obtained by measuring recognition accuracy as a function of cutoff frequency (in cycles per object).

Our data showed that critical cutoffs increased from central to peripheral vision by 20% for letter recognition and by 50% for face recognition. We asked whether these differences could be accounted for by central/peripheral differences in the contrast sensitivity function (CSF). We addressed this question by implementing an ideal-observer model which incorporates empirical CSF measurements and tested the model on letter and face recognition. The success of the model indicates that central/peripheral differences in the cutoff requirements for letter and face recognition can be accounted for by the information content of the stimulus limited by the shape of the human CSF, combined with a source of internal noise and followed by an optimal decision rule.

1. Introduction

People sometimes need to function near the spatial-resolution limit for pattern recognition. Examples include recognizing letters on a distant traffic sign while driving, or recognizing a familiar face across the street. In these cases, spatial resolution is limited by visual acuity. Factors besides acuity may also limit spatial resolution such as fog, low-resolution display rendering, refractive error or damage to the visual pathway from eye disease. The current study aims to address pattern recognition under conditions of low resolution.

Reading and face recognition are among the most common human visual activities. Besides their ecological significance, there is also theoretical importance for selecting these two categories in studying human pattern recognition. It is thought that faces are recognized holistically (e.g., Farah, 1991; Tanaka & Farah, 1993; Gauthier & Tarr, 2002), while letters are thought to be recognized based on simple features (e.g., Pelli et al., 2006). These two categories of objects are exemplars of two important kinds of pattern recognition.

Previous studies of letter and face recognition have shown that the human visual system requires spatial frequencies extending beyond some critical value, e.g., 1–3 cycles per letter (CPL) (Alexander, Xie, & Derlacki, 1994; Chung, Legge, & Tjan, 2002; Ginsburg, 1978; Gold, Bennett, & Sekuler, 1999; Legge et al., 1985; Parish & Sperling, 1991; Solomon & Pelli, 1994) and 3–16 cycles per face width (CPF) (Costen, Parker, & Craw, 1994; Fiorentini, Maffei, & Sandini, 1983; Ginsburg, 1980; Gold, Bennett, & Sekuler, 1999; Harmon, 1973; Harmon & Julesz, 1973; Hayes, Marrone, & Burr, 1986). The wide range of estimates for faces may be due to methodological differences across studies such as filtering techniques and number and type of faces (e.g., faces with or without hair).

Previous studies of spatial-frequency requirements for pattern recognition have employed psychophysical methods to determine the ranges of frequencies that yield optimal recognition performance. For example, Gold, Bennett, and Sekuler (1999) investigated the center frequencies critical for letter and face recognition. They measured contrast thresholds required to recognize two-octave
wide band-pass filtered letters and faces in the presence of external white noise at 67% accuracy level and defined the critical frequency as the bandwidth showing the largest ratio of ideal to human contrast threshold energy. Although methods requiring measurement of contrast thresholds for letters and faces in the presence of masking noise have yielded useful theoretical insights, they do not characterize recognition in the more ecologically common case of reduced spatial resolution. Moreover, little is known about how the minimum spatial-frequency requirements for pattern recognition differ in central and peripheral vision.

It is known that reading in peripheral vision is slow (Chung, Mansfield, & Legge, 1998; Rubin & Turano, 1994) and face recognition in peripheral vision is poor (Mäkelä et al., 2001) even with adequate magnification. People who lose their central vision due to diseases such as age-related macular degeneration (AMD) have to rely on their peripheral vision to read and recognize faces. It is important to gain a better understanding of what aspects of pattern recognition in peripheral vision differ from central vision for both theoretical and clinical reasons.

The primary goal of the present study is to examine whether there are differences in spatial-frequency requirements between central and peripheral vision for letter and face recognition. We measured recognition performance as a function of the cutoff frequency of a low-pass spatial-frequency filter. Minimum spatial-frequency cutoffs yielding criterion recognition accuracy (i.e., 80%) for 26 letters of the English alphabet and 26 celebrity faces were measured in both central and peripheral vision. We call this minimum spatial-frequency cutoff the critical cutoff, which represents the minimum spatial resolution allowing for reliable letter and face recognition. The critical cutoff for object recognition can be expressed in both retinal spatial frequency (cycles per degree, CPD) or object spatial-frequency (cycles per object, CPO). In this paper, cutoffs are usually expressed as object spatial frequencies. In order to find the critical cutoff for object recognition, one could fix angular object size, and allow retinal and object spatial frequency to covary. In this study, we, however, preferred to fix retinal spatial frequency and vary object spatial frequency by changing image size. This choice was made because an upper-bound on retinal spatial frequency is often imposed by physiology (e.g., the acuity limit). A retinal spatial frequency (1.5 CPD) was chosen as the cutoff because it could be studied in both foveal and peripheral vision (see more details in Section 2).

There are at least four reasons to expect that the spatial-frequency requirements of object recognition may be different in central and peripheral vision. First, because of acuity limitations, larger letters (or faces) are usually required for peripheral recognition. It has been shown that the optimal spatial frequency band shifts to higher object frequency (CPL) when letter size increases (Alexander, Xie, & Derlacki, 1994; Chung, Legge, & Tjan, 2002; Majaj et al., 2002). Second, there are studies showing that the human visual system can make use of both grayscale resolution (i.e., contrast coding) and spatial resolution for pattern recognition, (Farrell, 1991; Kwon & Legge, submitted for publication). If this is the case, the lower contrast sensitivity of the periphery (i.e., reduced range for contrast coding) might mean that the very low resolution stimuli that can be recognized in the fovea might not be recognizable in the periphery. Evidence for an interaction between contrast coding and spatial resolution in face recognition also comes from the work of Mäkelä et al. (2001). They measured contrast sensitivity for face identification in order to see if foveal and peripheral performance would become equivalent by magnification of image size only. They found that to achieve equivalent performance, however, both the size and contrast of images needed to increase in the periphery.

Third, pattern recognition in peripheral vision is known to suffer from crowding (Bouma, 1973), i.e., impairments in recognition performance due to interference from nearby flankers. Martelli, Majaj, and Pelli (2005) demonstrated that crowding occurs not only at the object level (e.g., face), but also at the part level (e.g., eye, nose, mouth). The crowding effect can be reduced by increasing spacing between parts of an object. Increasing spacing can be achieved by increasing the size of the object as a whole or by increasing the separation between parts while keeping the size of each part intact. These manipulations would result in a larger object size, which in turn might lead to a higher critical cutoff requirement in peripheral vision. Furthermore, Chung and Tjan (2007) showed that the human visual system shifts its sensitivity toward a higher spatial-frequency channel when identifying crowded letters, compared to single letters.

A fourth factor differing between central and peripheral vision and potentially affecting critical cutoffs for pattern recognition is the shape of the human contrast sensitivity function (CSF). Previous studies have demonstrated that the shape of the human CSF helps to explain the spatial-frequency characteristics of letter recognition and reading (Chung, Legge, & Tjan, 2002; Chung & Tjan, 2009; Gervais, Harvey, & Roberts, 1984; Legge, Rubin, & Luebker, 1987).

A secondary goal of the present study was to examine whether the difference, if any, in spatial frequency requirements in central and peripheral vision for pattern recognition can be accounted for by the human CSF. For this purpose, we implemented a model, similar to the CSF-ideal-observer model introduced by Chung, Legge, and Tjan (2002). We incorporated human CSFs for central and peripheral vision in the model, and asked if its performance in letter and face recognition resembled our human data.

2. Method

2.1. Subjects

Eighteen (letter recognition) and twelve (face recognition) college subjects (ages ranging from 19 to 25) were recruited from the University of Minnesota campus. They were all native English speakers with normal or corrected-to-normal vision and normal contrast sensitivity. The mean acuity (Lighthouse distance acuity chart) was −0.09 logMar (Snellen 20/16), and ranged from −0.24 (Snellen 20/11) to 0.04 (Snellen 20/22). The mean log contrast sensitivity (Pelli-Robson chart) was 1.84, and ranged from 1.65 to 2.05. Subjects were either paid $10.00 per hour or granted class credit for their participation. The experimental protocols were approved by the Internal Review Board (IRB) at the University of Minnesota and written informed consent was obtained from all subjects prior to the experiment.

2.2. Stimuli

2.2.1. Letter images

The 26 lower- and upper-case Courier font letters of the English alphabet were used for the letter recognition experiment. The letter images were constructed in Adobe Photoshop (version 8.0) and MATLAB (version 7.4). Letter size defined as x-height varied from 14 to 47 pixels (0.45−1.5") at a viewing distance of 60 cm). A single black letter was generated on a uniform gray background of 250 × 250 pixels.

2.2.2. Face images

Images of 26 well-known celebrities (13 females and 13 males) were selected from the Google image database. The set of 26 faces was selected from a larger set of 50 celebrity faces using a familiarity survey administered to 15 college students. Survey respondents were given a 2 × 2 in. photo of a celebrity’s face. They had to fill out the name of each celebrity and rank how familiar they were with the celebrity on a five-point scale. If they did not name the
2.2.3. Image filtering

The images were blurred using a 3rd order Butterworth low-pass filter in the spatial frequency domain. The filter was radially symmetric with a cutoff frequency of 1.5 CPD for letter or face), equivalent to 1.5 CPL for a 1° letter size. The filter function was as follows:

\[ f = \frac{1}{1 + (\frac{c}{r})^n} \]  

where \( r \) is the component radius, \( c \) is the low-pass cutoff radius and \( n \) is the filter’s order.

The filter’s response function is shown in Fig. 1. Fig. 2 shows sample letters and faces for both normal (top panels) and blurred images (bottom panels).

2.2.4. Image display on screen

To present the filtered images on the monitor, we mapped the luminance values of the letters to the 256 gray levels. The DC value of the filtered image was always mapped to the gray level of 127, equivalent to the mean luminance of the monitor (40 cd/m²). The stimuli were generated and controlled using MATLAB (version 7.4) and Psychophysics Toolbox extensions (Mac OS X) (Brainard, 1997; Pelli, 1997), running on a Mac Pro computer. The display was a 19" CRT monitor (refresh rate: 75 Hz; resolution: 1152 × 870, subtending 37° × 28° visual angle at a viewing distance of 60 cm). Luminance of the display monitor was made linear using an 8-bit look-up table in conjunction with photometric readings from a MINOLTA CS-100 Chroma Meter. The image luminance values were mapped onto the values stored in the look-up table for the display.

2.3. Measuring critical cutoff frequencies for letter and face recognition

Face and letter recognition measurements were conducted in separate experiments on different subject groups. Both experiments, however, used the same procedure.

Recognition performance was obtained for six cutoff frequencies specified in CPL. This was achieved by fixing the cutoff retinal spatial frequency at 1.5 CPD and using six image sizes. For example, for a letter size of 1°, the cutoff frequency in CPL was 1.5 CPL. It is also possible to find the critical cutoff frequency by fixing letter size and varying the retinal spatial-frequency cutoff of the filter. In order to check the consistency of our method, we also obtained critical cutoffs by measuring recognition accuracy by fixing stimulus size and varying retinal frequency. We obtained critical cutoffs for the uppercase foveal condition from three subjects. We found that the mean critical cutoff is 1.21 (±0.07) CPL for this condition, which is not statistically different from the critical cutoff frequency obtained by fixing retinal frequency and varying image size (\( p = 0.084 \)). This finding convinced us to believe that the two different procedures yield approximately the same results.

The critical cutoff was estimated from the resulting psychometric function, a plot of percent correct letter recognition as a function of cutoff frequency (Fig. 3). Best-fitting (least squares) cumulative Gaussian functions (Wichmann & Hill, 2001) were fit to the data and threshold was defined as the cutoff frequency yielding 80% correct responses (Fig. 3). The parameters alpha and beta are related to the mean and variance of the underlying Gaussian distribution, and determine the psychometric function’s location on the x-axis (alpha) and steepness (beta). Trials with six different cutoffs in CPL (or CPF) were randomly interleaved. Each cutoff was presented 100 times, so there were 600 trials for each psychometric function.

In each trial, subjects were presented with a blurry letter (a–z or A–Z) for 150 ms. Next, the displays were set to average luminance, and after a brief pause (500 ms), a set of 26 thumbnail versions of the letter images (56 × 56 pixels in size) appeared on the screen. Then, subjects identified the target stimulus by clicking the mouse on one of 26-letter answering keys forming a clock face. To prevent subjects from using any image matching strategy, a different font (Arial) and the opposite lettercase were used for the response key.

The location of each letter on the response key was shuffled every block to avoid any response bias induced by specific location. Subjects were given approximately 30 practice trials before the experimental test. A small cross in the center of the stimulus served as a fixation mark to minimize eye-movements throughout the experiment (only in the peripheral condition). A chin-rest was used to reduce head movements and to maintain the 60 cm viewing distance. Subjects were instructed to fixate on the fixation point on the computer screen during trials. The experimenter visually observed subjects to confirm that these instructions were being followed. The exposure time (150 ms) was too brief to permit useful eye movements.

Each letter and face recognition experiment consisted of four blocks: 2 lettercases (lower vs. uppercase letters) × 2 face types.
(faces with hair vs. without hair) × 2 visual field locations (fovea vs. periphery (10° lower visual field)). Thus, within a block, subjects were aware of both the type of target object and target location. The order of blocks was counterbalanced across subjects.

3. Results

3.1. Letter recognition in fovea and periphery

Fig. 4 shows one subject’s psychometric functions from fovea and periphery (left panel for lowercase and right panel for uppercase). As described in Section 2, a critical cutoff was estimated from a psychometric function and defined to be the cutoff yielding 80% correct responses. Critical cutoffs were larger in the periphery than the fovea for both letter cases (0.92 CPL vs. 1.10 CPL for lowercase; 1.06 CPL vs. 1.40 CPL for uppercase). The slope of the curve decreased from the fovea (black asterisks) to the periphery (red1 asterisks) for both lower- and uppercase letters. (The peripheral condition refers to 10° eccentricity in the lower visual field.) This pattern of results was fairly consistent across all the subjects.

We performed an analysis of variance (ANOVA) on cutoff frequency (CPL) – 2 (visual field: fovea, periphery) × 2 (lettercase: lower, upper) repeated measures ANOVA with visual field and lettercase as within-subject factors. There was a main effect of visual field ($F_{(1, 17)} = 119.08$, $p < 0.001$), indicating that critical cutoffs are significantly larger in the periphery than the fovea (20% larger on average). There was also a main effect of lettercase ($F_{(1, 17)} = 351.15$, $p < 0.001$), indicating that uppercase letters have larger critical cutoffs than lowercase letters. We also found a significant interaction effect between lettercase and visual field location ($F_{(1, 17)} = 7.59$, $p = 0.014$), indicating that the difference in critical cutoff between central and peripheral visual field is more pronounced for uppercase than lowercase letters.

As shown in Fig. 5, the mean critical cutoff for lowercase letters significantly increased from 0.90 CPL (±0.01) in the fovea to 1.06 CPL (±0.02) in the periphery and also increased for uppercase letters from 1.14 CPL (±0.02) in the fovea to 1.36 CPL (±0.02) in the periphery (all $p < 0.05$).

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1 For interpretation of color in Figs. 4, 6, 10–13, B.1–B.4 the reader is referred to the web version of this article.
Table 1 summarizes mean and standard errors for critical cut-offs. These differences are qualitatively unchanged for different threshold criteria ranging from 50% to 90%.

Changes in critical cutoffs could result from two possible influences on the psychometric function: (1) a horizontal shift of the curve along the cutoff axis, characterized by parameter alpha; or (2) a change in steepness of the curve, characterized by parameter beta. Our findings indicate that most of the effects on critical cutoff were due to changes in the slopes of the psychometric functions.

For both lowercase and uppercase letters, the slopes of the curves decreased substantially from the fovea to the periphery, as indicated by a significant increase in $b$ value. There was a 32% increase in $b$ value for lowercase letters in the periphery (Table 1). Even larger changes for uppercase letters were found, 35% increase in $b$ value.

### 3.2. Face recognition in fovea and periphery

Fig. 6 shows subject 2’s psychometric functions for the fovea and the periphery (left panel for face with hair and right panel for face without hair). Critical cutoffs were larger in the periphery than the fovea for both face types (1.97 CPF vs. 3.06 CPF for face with hair; 3.89 CPF vs. 5.07 CPF for face without hair). The slope of the curve decreased from the fovea (black asterisks) to the periphery (red asterisks) for both face types. This pattern of results was fairly consistent across all the subjects.

We performed an analysis of variance (ANOVA) on cutoff (CPF) – 2 (visual field: fovea, periphery) × 2 (face type: face with hair, face without hair) repeated measures ANOVA with face type and visual field as within-subject factors. There was a main effect of visual field ($F_{(1, 11)} = 18.63$, $p = 0.001$), indicating that critical cutoffs are significantly larger in the periphery than the fovea. There was also a main effect of face type ($F_{(1, 11)} = 38.54$, $p < 0.001$), showing that faces without hair require larger critical cutoffs than faces with hair. We also found a significant interaction effect between face type and visual field ($F_{(1, 11)} = 9.50$, $p = 0.01$), indicating that the difference in critical cutoff between central and peripheral visual field is more pronounced for faces without hair.

As shown in Fig. 7, the mean critical cutoffs for faces with hair increased from 2.59 CPF (±0.10) in the fovea to 3.31 CPF (±0.16) in the periphery and also for faces without hair from 4.23 CPF (±0.15) in the fovea to 7.32 CPF (±0.90) in the periphery. Table 2 summarizes mean and standard errors for critical cutoffs obtained from threshold criteria at 80% accuracy. The pattern of result stayed unchanged for different threshold criteria ranging from 50% to 90% accuracy.

For both face types, slopes of the psychometric functions were shallower in the periphery, accounting for the larger value of the critical cutoff. There was a 27% increase in $b$ value for faces with hair in the periphery. Even larger changes for faces without hair were found, 75% increase in $b$ value.

**Table 1**

Critical cutoffs (defined as the minimum cutoff to achieve 80% recognition accuracy) and parameter values of the psychometric functions for four different stimulus conditions ($n = 18$).

<table>
<thead>
<tr>
<th></th>
<th>Critical cutoff (CPF)</th>
<th>$\alpha$ (scale parameter)</th>
<th>$\beta$ (shape parameter)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lowercase in the fovea</td>
<td>0.90 (±0.01)</td>
<td>0.47 (±0.004)</td>
<td>0.15 (±0.006)</td>
</tr>
<tr>
<td>Lowercase in the periphery</td>
<td>1.06 (±0.02)</td>
<td>0.55 (±0.011)</td>
<td>0.19 (±0.008)</td>
</tr>
<tr>
<td>Uppercase in the fovea</td>
<td>1.14 (±0.02)</td>
<td>0.63 (±0.007)</td>
<td>0.15 (±0.005)</td>
</tr>
<tr>
<td>Uppercase in the periphery</td>
<td>1.36 (±0.02)</td>
<td>0.73 (±0.013)</td>
<td>0.21 (±0.007)</td>
</tr>
</tbody>
</table>


Fig. 4. Psychometric functions for subject 3: (a) lowercase letters and (b) uppercase letters. Data from the fovea are shown as black asterisks and periphery as red crosses (see Footnote 1). The dotted lines are the best fits of a cumulative Gaussian function.

Fig. 5. Critical cutoffs in the fovea and the periphery for lowercase and uppercase letters ($n = 18$).
4. Model description and comparison with human performance

4.1. Model overview

We now describe the implementation of a CSF-noise-ideal-observer model (hereafter the model) for letter and face recognition in central and peripheral vision. The aim of our modeling was to determine if our human results could be accounted for by a small set of assumptions about early visual processing combined with an optimal decision rule. To the extent that human performance matches model performance, we can pinpoint stimulus-based factors that may account for central–peripheral changes in human pattern recognition.

In principle, an ideal observer is able to perform with 100% accuracy in a recognition task if the stimuli are noise free. For this reason, many prior studies comparing human performance to an ideal observer have included noise-perturbed stimuli so that ideal performance drops below ceiling. In our study, no external noise was added to the stimulus. Instead, we constructed the model to have a source of additive noise following stimulus encoding and prior to the decision process (hereafter we call the stimulus with added noise “noisy input stimulus” for convenience).

The model contained a CSF filter and additive noise source placed between the stimulus and an optimal classifier as depicted in Fig. 8. The CSF filter was a linear filter with a shape identical to a human CSF.

The decision process in the model knows the exact pixel representations of the set of possible low-pass-filtered stimulus images and the probability of occurrence of the letters (the 26 letters are equally probable). The model also knows the statistics of the added luminance noise and the weighting associated with the CSF filter. In each simulation trial, the input to the model is a low-pass filtered letter or face image. The model makes full use of task-relevant information and makes a recognition response to maximize performance (percent correct) via a strategy of choosing the maximum posterior probability of the input being a particular target given the noisy image available to the decision process (Green & Swets, 1966; Tanner & Birdsall, 1958). The computation of finding the maximum posterior probability is equivalent to minimizing the Euclidean distance between the noisy input stimulus and its stored noiseless template (e.g., 26 letters or faces), often called template

2 The CSF filter can be viewed as frequency-dependent noise. White noise is added after the CSF filter so that the signal-to-noise ratio across spatial frequencies followed the shape of the CSF. The performance of the ideal observer is determined by signal-to-noise ratio (SNR). Incorporating the human CSF into the ideal observer model is essentially equivalent to modifying SNR in a frequency-dependent way by introducing frequency-dependent noise (see Chung & Tjan, 2009; Pelli, 1990, pp. 3–24), i.e., additive noise whose shape follows the inverse of the CSF. We can formulate the outcome of the ideal and CSF-noise-ideal observers in terms of object signal and noise as follows:

\[ \text{CSF-noise-ideal observer} = f(S + N(freq) + N_0) \]

where \( S \) is a target signal, \( N_0 \) is constant noise and \( N(freq) \) is a frequency-dependent noise that mimics the effect on SNR of the CSF filter.

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Table 2
Critical cutoffs and parameter values of psychometric functions for four different stimulus conditions (n = 12).

<table>
<thead>
<tr>
<th>Cutoff Condition</th>
<th>Cutoff (CPF)</th>
<th>( \alpha ) (scale parameter)</th>
<th>( \beta ) (shape parameter)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Faces with hair in the fovea</td>
<td>2.59 (±0.10)</td>
<td>1.64 (±0.07)</td>
<td>1.13 (±0.06)</td>
</tr>
<tr>
<td>Faces with hair in the periphery</td>
<td>3.31 (±0.16)</td>
<td>1.83 (±0.10)</td>
<td>1.76 (±0.19)</td>
</tr>
<tr>
<td>Faces without hair in the fovea</td>
<td>4.23 (±0.15)</td>
<td>2.75 (±0.09)</td>
<td>1.76 (±0.13)</td>
</tr>
<tr>
<td>Faces without hair in the periphery</td>
<td>7.32 (±0.90)</td>
<td>4.02 (±0.30)</td>
<td>3.92 (±0.82)</td>
</tr>
</tbody>
</table>

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Fig. 6. Psychometric functions of subject 2: (a) faces with hair and (b) faces without hair. Data from the fovea are shown as black asterisks and periphery as red crosses (see Footnote 1). The dotted lines are the best fits of a cumulative Gaussian function.

Fig. 7. Critical cutoffs in the fovea and the periphery for faces with hair and faces without hair (n = 12).
matching (Details of this computational derivation are provided in Appendix A).

The model’s performance was based on Monte Carlo simulations of 21,000 trials per psychometric function. Recognition performance of the model was measured for input stimuli with seven cutoff frequencies, yielding performance levels from 10% correct to 95% correct. There were 3000 trials for each cutoff level. A psychometric function, a plot of recognition accuracy vs. cutoff frequency, was created by fitting the data with a cumulative Gaussian function. The critical cutoff was defined as the spatial frequency yielding 80% correct on the psychometric function.

Our model used empirical CSFs from Chung and Tjan (2009). Their CSFs were measured in the fovea and at 10°/C176 eccentricity in the lower visual field (Fig. 9) using stimulus parameters similar to those of our study.3

4.2. Comparing model and human recognition

4.2.1. Fitting the model to human recognition data by varying the noise parameter

We constructed plots of the model’s recognition accuracy as a function of spatial-frequency cutoff for comparison with human data (cf., Fig. 10). The steepness and position along the frequency axis of the model’s psychometric function depend on both the amplitude of the model’s internal noise and the featural similarity of the test targets. Before comparing human and model performance, we briefly discuss how these factors interact in determining the shape of the model’s psychometric functions.

It has been proven that in a pattern recognition task among N targets, percent correct (or d’-prime) is monotonically related to mean Euclidean distance between all pairs of targets (Geisler, 1985; Luce, 1963). Given a fixed level of noise, a set of targets with greater separation in feature space will yield better performance than a set of more similar targets. Putting this another way, the more similar the stimuli, the lower the noise amplitude required to push down recognition performance to a criterion threshold level. In our study, recognition performance is influenced by three factors: (1) the intrinsic featural similarity of the target stimuli (e.g., uppercase letters have a higher featural similarity than lowercase letters which contain distinctive ascenders and descenders, and faces without hair have a higher similarity than faces with hair); (2) increasing blur produces increased similarity by filtering out distinguishing fine pattern details; and (3) the amplitude of added noise. In our empirical procedure, spatial-frequency cutoff (blur) was the independent variable used for generating a psychometric function. We would expect that the position of our subjects’ psychometric functions on the spatial-frequency axis would depend on both the similarity of their perceptual representations of the stimuli and their internal noise. For our ideal-observer model, the position of the psychometric function is, thus, determined by the similarity of the digitally filtered stimulus images and the model’s internal noise.

The only free parameter in the model is the amplitude of the internal noise which we varied to seek a good match between human and model performance. As shown in Table 3, a separate value of the model’s noise parameter was obtained for each experimental condition. To summarize:

1. For both letters and faces, central vision required a smaller noise value than the periphery. This is likely because the human internal noise is higher in the periphery than in central vision.
2. A lower noise level was required for uppercase than lowercase letters, and also a lower noise level for faces without hair than for faces with hair. This is likely due to differences in stimulus similarity rather than differences in internal noise.
3. A much larger noise level was required for faces than letters. While this difference might reflect higher internal noise in the human face processing system, we believe that the difference is more likely due to factors

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3 The CSFs were measured using an orientation discrimination task for sine-wave gratings windowed by Gaussian profiles with 150 ms exposure duration (see more details in Chung and Tjan (2009)). The threshold values and the general shape of our CSFs are comparable to those reported in previous grating detection studies (De Valois, Morgan, & Snodderly, 1974; Virsu & Rovamo, 1979).
related to perceptual similarity of faces. We will return to this issue.

We tested whether the model fits are significantly better when separate noise values were used for different stimulus conditions by comparing the models with separate noise levels for the eight different sets of stimuli and models with fewer independent noise levels (e.g., the eight noise levels were reduced to two levels: one for the fovea and the other for the periphery by using the mean noise levels for the four sets of central stimuli and four sets of peripheral stimuli). Statistical tests (i.e., the nested model test and a goodness of fit test) suggested that having different internal noise levels for different stimulus conditions was required for the model to satisfactorily explain human recognition data.4 Appendix B also addresses whether the inclusion of the CSF in the ideal observer model is important for accounting for our human data. As the appendix illustrates, the model fits are much better when the CSF is included.

4.2.1.1. Letters. Fig. 10 compares the letter recognition performance of the model to human observers. Except for the upper-case foveal condition, it is evident that the model provides a good account of human letter recognition data. Particularly, in the case of lowercase letters (Fig. 10a), the data from the model nearly aligned with those of human observers. The quantitative analysis using a goodness of fit test ($\chi^2$ test) confirmed that the model provides a good account of human letter recognition performance for three of the four stimulus conditions (all $p > 0.05$). The exception is the upper-case foveal condition. What caused the poorer model fit for this condition is uncertain. Similar to humans, the model had larger critical cutoffs in peripheral vision than central vision for both letter cases (0.88 CPL in the fovea and 1.02 CPL in the periphery for lowercase letters; 1.12 CPL in the fovea and 0.88 CPL in the periphery for uppercase letters). The larger critical cutoff in peripheral vision appeared to result primarily from changes in the slope of the psychometric function, a consequence of the higher noise level required for the model to fit the human data in the periphery.

4.2.1.2. Faces. We also found that the model provides a satisfactory account for human face recognition data (Fig. 11). A goodness of fit test ($\chi^2$ test) further confirmed that the model provides a good account of human face recognition performance for all four stimulus conditions (all $p > 0.05$). Similar to humans, the model had larger critical cutoffs in peripheral than central vision for both face types: 2.29 CPL in the fovea and 3.24 CPL in the periphery for faces with hair; 4.09 CPL in the fovea and 7.14 CPL in the periphery for faces without hair. As is evident from Table 3, the model required much higher levels of noise to match the human face-recognition data than the human letter-recognition data. A consequence is the substantially higher critical cutoff frequencies for faces.

4.2.2. Model performance with fixed noise

As discussed above, the location and shape of the model’s psychometric function depend on both the amplitude of internal noise and the similarity of the set of stimuli. In the preceding subsection, we treated the model’s noise amplitude as a parameter and found that noise values could be selected to provide a good match between the model and human data. But this leaves unclear the impact of pattern similarity within our four sets of stimuli. We addressed this issue by fixing the noise amplitude to determine how the model’s psychometric functions depend on the nature of the stimulus sets.

In Fig. 12, the model’s psychometric functions are shown for the four sets of stimuli in central vision with the noise value held constant. The fixed noise value was 0.43, the value required to provide a match to the human data for lowercase letters. The corresponding human psychometric functions are also shown. As expected from the selection of the fixed noise level, the human and model psychometric functions coincide for the lowercase letters. The model’s psychometric function shifts slightly rightward for the uppercase letters compared to the lowercase letters as expected from our intuition that uppercase letters have greater featural similarity than lowercase letters. The human psychometric function shows a similar rightward shift. Surprisingly, however, the model’s psychometric functions for the two sets of face stimuli (with and without hair) are quite similar to the psychometric functions for the letters (e.g., critical cutoffs of 0.9 CPL for lowercase letters, 1.2 CPL for uppercase letters, 0.56 CPF for faces with hair, and 1.02 CPF for faces without hair). This implies that for the model, the featural similarity of the sets of faces is not very

![Fig. 11. Face recognition performance of the model in the fovea (black asterisks) and the periphery (red crosses) and for human observers (green open squares). Data were fitted with a cumulative Gaussian function.](image-url)
different from the sets of letters. On the other hand, the human psychometric functions for the faces are displaced substantially rightward on the spatial-frequency axis, and have much higher critical cutoffs for faces than letters. The discrepancy in Fig. 12 between the human and model psychometric functions for faces implies that either the human face-recognition system has much higher internal noise than the letter-recognition system, or that the encoding of faces in human perception results in the loss of distinguishing features that remain available for the model’s optimal classifier.

As indicated in Table 3, we found that in order to make the model fit the human data in the periphery, the noise parameter value of the model had to be increased by a factor of approximately 1.4 compared to the value in the fovea. Since the same two stimulus sets were used between central and peripheral vision, this finding can be explained by attributing 40% greater internal noise to the periphery at 10°.

Consistent with the findings in central vision, if we fix the peripheral noise level at the amplitude required to fit the lowercase letter data, there is a large discrepancy between human and model psychometric functions for faces (e.g., critical cutoff frequencies of 1.05 CPL for lowercase letters, 1.5 CPL for uppercase letters, 0.67 CPF for faces with hair, and 1.3 CPF for faces without hair) in peripheral vision (Fig. 13).

5. Discussion and conclusions

In the current study, we asked whether properties of peripheral vision might result in higher spatial-frequency-cutoff requirements for pattern recognition. Our secondary goal was to assess the impact of the human CSF in accounting for central and peripheral differences. We implemented the CSF-noise-ideal observer which incorporates empirical CSFs into an ideal observer model. We summarize our findings as follows:

1. We found that the critical cutoffs of human observers are significantly larger in peripheral than central vision, by an average of 20% for letters and 50% for faces. Our model analysis showed that even after taking the CSF into account, peripheral vision requires a larger critical cutoff for object recognition. This can be explained by an approximately 40% increase in noise from central vision to peripheral vision. This difference in critical cutoff between central and peripheral vision may contribute to the reading and face-recognition difficulties of people with central-field loss.

2. Our results showed that high levels of object-recognition accuracy are possible with quite low cutoffs. Despite the wide range of estimates among studies (cited in the Introduction), there has been a growing consensus that the spatial frequencies of 2–3 CPL and 8–16 CPF are the most crucial for identifying letters and faces respectively. However, we have found that people can achieve 80% recognition accuracy even with spatial-frequency cutoffs of 0.9 CPL and 2.6 CPF. These discrepancies between our findings and the previous studies are probably due to the distinction between the minimum spatial-frequency cutoffs required for pattern recognition (our study) and the optimal bands of spatial frequencies for pattern recognition identified in other studies (e.g., Gold, Bennett, & Sekuler, 1999). Data reported in Loomis (1990) also showed that low-pass filtered letters with a cutoff frequency of approximately 0.9 CPL yield reliable recognition performance (85–90% accuracy): Evidence that low object spatial-frequencies can support pattern identification has also been reported by Bondarko and Danilova (1997).
The low cutoffs may seem to contradict the conventional idea that letter recognition relies on the shape and arrangement of individual features (such as line segments and curves). This is because the cutoff frequency of 0.9 CPL has an equivalent sampling rate less than $2 \times 2$ samples per letter\(^5\) (Shannon, 1949), and fewer than four binary samples would permit discrimination among fewer than 16 patterns, not adequate for discriminating among 26 letters. In a follow-up study (Kwon & Legge, submitted for publication), we addressed this apparent discrepancy by testing the hypothesis that the human visual system relies increasingly on grayscale coding (contrast coding) for letter recognition when spatial resolution is severely limited.

Our model analysis with a fixed noise level showed that the model requires much higher critical cutoffs for uppercase letters than lowercase letters and for faces without hair than faces with hair. The results are consistent with those of human observers. This suggests that differences in spatial frequency requirements between uppercase and lowercase letters and between faces with and without hair are mostly driven by the inherent properties of stimuli (especially the featural similarity of members of a set of stimuli).

How general are our results? We acknowledge that using different sets of letters (e.g., fonts), or face images (e.g., a larger number of faces, or different face poses) might have resulted in different critical cutoff frequencies. Nonetheless, to the extent that the model was fit to the human data using one free parameter (the amplitude of the additive noise). This evidence of our modeling suggests that the minimum spatial-resolution requirements of human pattern recognition can be accounted for by a simple front-end sensory model which contains the properties of the stimulus, combined with the filtering properties of the human CSF and a source of internal noise, and followed by an optimal decision rule.

(6) Our ideal-observer model's performance exhibited one marked difference from human performance. When the model had a fixed noise level, its critical cutoffs for face recognition were lower than those for letter recognition. Humans showed the opposite -- higher critical cutoffs for faces than letters. What accounts for this discrepancy?

Humans may have a much less detailed representation of faces than letters, so that the effective stimulus similarity in our sets of faces was greater than for our sets of letters. In our experiment, we compelled subjects to choose from among a set of 26 faces. But, in the real world, people must encode information about a much larger set of faces. The strategies for representing a large number of faces may take advantage of configural data distributed more broadly across the frequency spectrum with sparser representation of low-frequency information. But coarse low-frequency features that survive severe blur may be effective for letter recognition which needs to distinguish only among 26 letters.

It is also possible that the discrepancy arises because the human face-recognition system is much noisier than the letter-recognition system. Higher noise would translate into a larger critical cutoff frequency for a given criterion level of performance.

In conclusion, our results show that the spatial-frequency-cutoff for pattern recognition is higher in peripheral than central vision. This difference can be accounted for by the CSF-noise-ideal observer model. In the context of the model, the central/peripheral differences can be traced to differences in the CSF and the overall amplitude of internal noise. The greater spatial-frequency requirements for human face recognition than letter recognition implies either a greater level of internal noise in human face processing or differences in human coding strategies for letters and faces.

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Appendix A. Decision rule of the CSF-noise-ideal observer for the recognition task

The CSF-noise-ideal observer has to solve the inverse optics problem, which is to figure out the most probable target signal ($T_i$) out of all possible 26 target signals ($T$) for a given input retinal image $R$, arrays of luminance pixel values. The problem can be expressed as $P(T_i|R)$ and can be solved using Bayes' rule as follows:

$$P(T_i|R) = \frac{P(R|T_i)P(T_i)}{P(R)} = \frac{P(R|T_i)P(T_i)}{\sum_{i=1}^{26} P(R|T_i)P(T_i)} \quad (A.1)$$

Since the denominator $P(R)$, which is just a normalizing constant can be removed from the equation, $P(T_i|R)$ can be reduced to the product of the likelihood function $P(R|T_i)$ and the prior probability $P(T_i)$ of a target signal.

---

\(^5\) In signal processing, the Nyquist rate is the maximum sampling rate which can be transmitted through a channel, which is equal to two times the highest frequency contained in the signal.
Then, at each pixel, we can compute the possible probability value by the likelihood function of a given noisy input image \( R \) as a function of all possible noiseless templates \( T_i \), and choose the highest possible \( T_i \) as its recognition response. The input image \( R \) is represented as an array of luminance pixel values and is added to zero-mean Gaussian luminance noise, \( \sigma \). Thus, let's say there is the \( m \) number of pixels in the input image \( R \) and \( R_j \) be the \( j \)th pixel in the image \( R \). Then, at each pixel, we can compute the possible probability value of the noiseless signal \( T_j \) in noisy input \( R_j \) since it has a Gaussian probability density function as follow:

\[
P(R_j|T_j) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma^2} \left| R_j - T_j \right|^2 \right)
\]

(A.4)

Since the luminance noise at different pixels is a random sample which is identically and independently distributed, i.i.d., the probability of the entire input image \( R \) is the product of the probabilities of all the pixels.

\[
P(R|T) = \prod_{j=1}^{m} P(R_j|T_j)
\]

(A.5)

\[
= \frac{1}{(\sigma\sqrt{2\pi})^m} \exp\left(-\frac{1}{2\sigma^2} \sum_{j=1}^{m} |R_j - T_j|^2 \right)
\]

(A.6)

\[
= \frac{1}{(\sigma\sqrt{2\pi})^m} \exp\left(-\frac{1}{2\sigma^2} \left| R - T \right|^2 \right)
\]

(A.7)

After removing terms that do not depend on \( i \) or \( j \) from Eq. (A.7), the likelihood function is \( P(R|T) \) is reduced to the following exponential function:

\[
P(R|T) = \exp\left(-\left| R - T \right|^2 \right)
\]

(A.8)

Inspection of Eq. (A.8) tells us that the likelihood function \( P(R|T) \) is monotonically related to \( |R - T|^2 \). In other words, maximizing Eq. (A.8) is the same as minimizing the Euclidean distance \( |R - T|^2 \) between the input image \( R \) and a template \( T \). In other words, the ultimate job of the ideal observer, which is to find the maximum posterior probability is equivalent to finding the smallest Euclidean distance between the noiseless template \( T \) and noisy input image \( R \).

Appendix B. Model selection

We compared one version of the ideal-observer model using a CSF and one without the CSF to see if inclusion of the CSF provides a better description of human performance data.

As described earlier, a wide range of white noise (\( \sigma^2 \)) levels was applied to the stimulus to find the noise level providing best fit to human recognition data. For each model, a family of psychometric functions from eight different noise levels was built for each given stimulus condition. For each model, we selected the best fit psychometric function to that of humans among a family of eight curves. Then, the two best psychometric functions from each model were compared using statistical F-test in which the model with a least mean squared error value was chosen as a superior model. Each psychometric function was constructed based on seven cutoffs. There was one free parameter, the constant noise \( N_0 \) for each model.

Figs. B.1 and B.2 demonstrate the goodness of fit of each model to human data (left column from the model without the CSF vs. right column from the model with the CSF). Each panel contains four psychometric functions: three from the ideal (black asterisks) and one (red crosses) from humans. For convenience, we only plotted three of them from the family of eight curves and compared them with those for human observers. The middle curves in the set of three in each panel are considered to be the best model fit to human recognition data.

Figs. B.1 and B.2 clearly demonstrate that the model with the CSF is superior to describe the human data for all four stimulus conditions. For example, as shown in Fig. B.1c and d from the lowercase letter, the curves from the model with the CSF completely aligned with those of humans. In the case of the uppercase letter, the fit was not as good as lowercase letters, but the model with
the CSF was still better than the model without the CSF. Quantitative analysis using F-test further confirmed that the model with the CSF was a better model than the model without the CSF for all four stimulus conditions (all \( p < 0.002 \)). Table B.1 summarizes residual sum of squares from the two models.

Based on our model selection analysis, we used the best fit data from the model with the CSF to examine spatial-frequency requirements in the fovea and the periphery in comparison with human recognition data.

### B.2. Model selection for face recognition

Consistent with letter recognition data, the model with the CSF provided a better account of the human recognition data for all four stimulus conditions (Figs. B.3 and B.4). For example, as shown in Figs. B.3c and B.4c the curve from the model with the CSF nearly overlapped with that from humans. The quantitative analysis using F-test further confirmed that the model with the CSF is superior to the model without the CSF for all four stimulus conditions (all \( p < 0.002 \)). Relatively larger variance in human face recognition data might have contributed to slightly less satisfactory fit between humans and the model. Table B.2 summarizes residual sum of squares from the two models.

Given the fact that the model with the CSF gives a better account of human face recognition, we used the best fit data from this model to examine spatial-frequency requirements in the fovea and the periphery in comparison with human recognition data.

### Table B.1

Residual sum of squares (RSS) of the two models for letter recognition.

<table>
<thead>
<tr>
<th></th>
<th>Lowercase in the fovea</th>
<th>Lowercase in the periphery</th>
<th>Uppercase in the fovea</th>
<th>Uppercase in the periphery</th>
</tr>
</thead>
<tbody>
<tr>
<td>RSS(_{model}) without CSF (df = 6)</td>
<td>0.108</td>
<td>0.071</td>
<td>0.330</td>
<td>0.151</td>
</tr>
<tr>
<td>RSS(_{model}) with CSF (df = 6)</td>
<td>0.004</td>
<td>0.001</td>
<td>0.056</td>
<td>0.022</td>
</tr>
</tbody>
</table>

### Table B.2

Residual sum of squares (RSS) of the two models for face recognition.

<table>
<thead>
<tr>
<th></th>
<th>Lowercase in the fovea</th>
<th>Lowercase in the periphery</th>
<th>Uppercase in the fovea</th>
<th>Uppercase in the periphery</th>
</tr>
</thead>
<tbody>
<tr>
<td>RSS(_{model}) without CSF (df = 6)</td>
<td>0.347</td>
<td>0.245</td>
<td>0.448</td>
<td>0.211</td>
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<tr>
<td>RSS(_{model}) with CSF (df = 6)</td>
<td>0.013</td>
<td>0.041</td>
<td>0.005</td>
<td>0.037</td>
</tr>
</tbody>
</table>

### References


